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1 Derivative $\frac{\partial J_m(\underline{\sigma})}{\partial \underline{\sigma}}$

Here I am going to describe the possible problem with the derivation of the aforementioned derivative $\frac{\partial J_m(\underline{\sigma})}{\partial \underline{\sigma}}$ in the paper by Masatsugu Yaguchi and Yukio Takahashi “Ratchetting of viscoplastic material with cyclic softening, part 2: application of constitutive models”, International Journal of Plasticity 21 (2005) 835-860, when taking into account the tension–compression asymmetry. It is also possible though that it is just my misunderstanding of the derivation. If it is the later, could you please give some details on where a flaw might be in my derivations?

The term that takes into account the tension=–compression asymmetry is

$$J_m(\underline{\sigma}) = \eta |\text{tr } \underline{\sigma}|^l \text{sgn}(\text{tr } \underline{\sigma}), \quad (1)$$

where η and l are constants.

Then later in the paper its derivative with respect to $\underline{\sigma}$ is taken:

$$\dot{\epsilon}_{\text{in}[m]} = \dot{p} \frac{l J_m(\underline{\sigma})}{|\text{tr } \underline{\sigma}|} \underline{I} = \dot{p} \frac{\partial J_m(\underline{\sigma})}{\partial \underline{\sigma}} = \dot{p} l \eta |\text{tr } \underline{\sigma}|^{l-1} \text{sgn}(\text{tr } \underline{\sigma}) \underline{I}. \quad (2)$$

So according to the paper

$$\frac{\partial J_m(\underline{\sigma})}{\partial \underline{\sigma}} = l \eta |\text{tr } \underline{\sigma}|^{l-1} \text{sgn}(\text{tr } \underline{\sigma}) \underline{I}. \quad (3)$$

When I tried to repeat the derivation, I came up with

$$\frac{\partial J_m(\underline{\sigma})}{\partial \underline{\sigma}} = \frac{\partial}{\partial \underline{\sigma}} [\eta |\text{tr } \underline{\sigma}|^l \text{sgn}(\text{tr } \underline{\sigma})] = \eta \left[\frac{\partial}{\partial \underline{\sigma}} (|\text{tr } \underline{\sigma}|^l) \text{sgn}(\text{tr } \underline{\sigma}) + |\text{tr } \underline{\sigma}|^l \frac{\partial}{\partial \underline{\sigma}} (\text{sgn}(\text{tr } \underline{\sigma})) \right]. \quad (4)$$

Where

$$\frac{\partial}{\partial \underline{\sigma}} (|\text{tr } \underline{\sigma}|^l) = l |\text{tr } \underline{\sigma}|^{l-1} \text{sgn}(\text{tr } \underline{\sigma}) \underline{I} \quad (5)$$

and

$$\frac{\partial}{\partial \underline{\sigma}} (\text{sgn}(\text{tr } \underline{\sigma})) = 2\delta(\text{tr } \underline{\sigma}) \underline{I}, \quad (6)$$

where δ is the Dirac delta function. Alternatively, we can say that $\frac{\partial}{\partial \underline{\sigma}} (\text{sgn}(\text{tr } \underline{\sigma}))$ is $\underline{0}$ (tensor with all components equal to zero) everywhere where $(\text{tr } \underline{\sigma})$ is non-zero.

Combining (4), (5) and (6) we get

$$\frac{\partial J_m(\underline{\sigma})}{\partial \underline{\sigma}} = \eta l |\text{tr } \underline{\sigma}|^{l-1} \text{sgn}(\text{tr } \underline{\sigma}) \underline{I} \text{sgn}(\text{tr } \underline{\sigma}) + \eta |\text{tr } \underline{\sigma}|^l 2\delta(\text{tr } \underline{\sigma}) \underline{I}. \quad (7)$$

Taking into account the relationship $(\text{tr } x)^2 = 1$ (for any $x \neq 0$) and the fact that $\delta(x) = 0$, for $x \neq 0$ we can simplify (7) to

$$\frac{\partial J_m(\underline{\sigma})}{\partial \underline{\sigma}} = \eta l |\text{tr } \underline{\sigma}|^{l-1} \underline{I}. \quad (8)$$

As you can see, the derivative (3) obtained in the paper differ from the derivative (8) obtained here.

Is the derivation correct?